

## Classification of $Aff(2, \mathbb{R})$ -orbit's dimensions for quadratic differential system

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**Abstract.** Affine invariant conditions for  $Aff(2, \mathbb{R})$ -orbit's dimensions are defined for two-dimensional autonomous quadratic differential system.

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Consider two-dimensional quadratic differential system

$$\frac{dx^j}{dt} = a^j + a_{\alpha}^j x^{\alpha} + a_{\alpha\beta}^j x^{\alpha} x^{\beta} \quad (j, \alpha, \beta = \overline{1, 2}), \quad (1)$$

where the coefficient tensor  $a_{\alpha\beta}^j$  is symmetrical in lower indices in which the complete convolution holds.

Consider also the group  $Aff(2, \mathbb{R})$  of affine transformations given by the equalities:

$$\bar{x}^1 = \alpha x^1 + \beta x^2 + h^1, \quad \bar{x}^2 = \gamma x^1 + \delta x^2 + h^2, \quad \Delta = \det \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \neq 0,$$

where  $\alpha, \beta, \gamma, \delta, h^1, h^2$  take real values.

Further will use the notations

$$\begin{aligned} a^1 &= a, & a^2 &= b, & a_1^1 &= c, & a_2^1 &= d, & a_1^2 &= e, & a_2^2 &= f, & a_{11}^1 &= g, & a_{12}^1 &= h, \\ a_{22}^1 &= k, & a_{11}^2 &= l, & a_{12}^2 &= m, & a_{22}^2 &= n, & x^1 &= x, & x^2 &= y. \end{aligned} \quad (2)$$

According to [1] and taking into consideration (2), the representation operators of the group  $Aff(2, \mathbb{R})$  in the space of coefficients and variables of the system (1) will

take the form

$$\begin{aligned}
 X_1 &= x \frac{\partial}{\partial x} + a \frac{\partial}{\partial a} + d \frac{\partial}{\partial d} - e \frac{\partial}{\partial e} - g \frac{\partial}{\partial g} + k \frac{\partial}{\partial k} - 2l \frac{\partial}{\partial l} - m \frac{\partial}{\partial m}, \\
 X_2 &= y \frac{\partial}{\partial x} + b \frac{\partial}{\partial a} + e \frac{\partial}{\partial c} + (f - c) \frac{\partial}{\partial d} - e \frac{\partial}{\partial f} + l \frac{\partial}{\partial g} + \\
 &\quad + (m - g) \frac{\partial}{\partial h} + (n - 2h) \frac{\partial}{\partial k} - l \frac{\partial}{\partial m} - 2m \frac{\partial}{\partial n}, \\
 X_3 &= x \frac{\partial}{\partial y} + a \frac{\partial}{\partial b} - d \frac{\partial}{\partial c} + (c - f) \frac{\partial}{\partial e} + d \frac{\partial}{\partial f} - 2h \frac{\partial}{\partial g} - k \frac{\partial}{\partial h} + \\
 &\quad + (g - 2m) \frac{\partial}{\partial l} + (h - n) \frac{\partial}{\partial m} + k \frac{\partial}{\partial n}, \\
 X_4 &= y \frac{\partial}{\partial y} + b \frac{\partial}{\partial b} - d \frac{\partial}{\partial d} + e \frac{\partial}{\partial e} - h \frac{\partial}{\partial h} - 2k \frac{\partial}{\partial k} + l \frac{\partial}{\partial l} - n \frac{\partial}{\partial n}, \\
 X_5 &= \frac{\partial}{\partial x} - c \frac{\partial}{\partial a} - e \frac{\partial}{\partial b} - 2g \frac{\partial}{\partial c} - 2h \frac{\partial}{\partial d} - 2l \frac{\partial}{\partial e} - 2m \frac{\partial}{\partial f}, \\
 X_6 &= \frac{\partial}{\partial y} - d \frac{\partial}{\partial a} - f \frac{\partial}{\partial b} - 2h \frac{\partial}{\partial c} - 2k \frac{\partial}{\partial d} - 2m \frac{\partial}{\partial e} - 2n \frac{\partial}{\partial f}.
 \end{aligned} \tag{3}$$

The operators (3) form a six-dimensional Lie algebra [1]. Let  $\tilde{a} = (a, b, \dots, n) \in E^{12}(\tilde{a})$ , where  $E^{12}(\tilde{a})$  is the Euclidean space of the coefficients of the right-hand sides of the system (1). Denote by  $\tilde{a}(q)$  the point from  $E^{12}(\tilde{a})$  that corresponds to the system, obtained from the system (1) with coefficients  $\tilde{a}$  by a transformation  $q \in Aff(2, \mathbb{R})$ .

**Definition 1.** Call the set  $O(\tilde{a}) = \{\tilde{a}(q) | q \in Aff(2, \mathbb{R})\}$  the  $Aff(2, \mathbb{R})$  - orbit of the point  $\tilde{a}$  for the system (1).

It is known from [1] that

$$dim_{\mathbb{R}} O(\tilde{a}) = rank M_1, \tag{4}$$

where  $M_1$  is the following matrix

$$M_1 = \begin{pmatrix} a & 0 & 0 & d & -e & 0 & -g & 0 & k & -2l & -m & 0 \\ b & 0 & e & -c+f & 0 & -e & l & -g+m & -2h+n & 0 & -l & -2m \\ 0 & a & -d & 0 & c-f & d & -2h & -k & 0 & g-2m & h-n & k \\ 0 & b & 0 & -d & e & 0 & 0 & -h & -2k & l & 0 & -n \\ -c & -e & 2g & -2h & -2l & -2m & 0 & 0 & 0 & 0 & 0 & 0 \\ -d & -f & 2h & -2k & -2m & -2n & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \tag{5}$$

constructed on coordinate vectors of operators (3). Denote by  $\Delta_{i,j,k,l,m,n}$  the minor of the 6th order of the matrix  $M_1$ , constructed on columns  $i, j, k, l, m, n$  ( $i, j, k, l, m, n \in \{1, \dots, 12\}$ ).

For the system (1) from [2], [4] are known the following center-affine comitants and invariants

$$\begin{aligned}
I_1 &= a_\alpha^\alpha, \quad I_2 = a_\beta^\alpha a_\alpha^\beta, \quad I_3 = a_p^\alpha a_{\alpha q}^\beta a_{\beta \gamma}^\gamma \varepsilon^{pq}, \quad I_4 = a_p^\alpha a_{\beta q}^\beta a_{\alpha \gamma}^\gamma \varepsilon^{pq}, \\
I_5 &= a_p^\alpha a_{\gamma q}^\beta a_{\alpha \beta}^\gamma \varepsilon^{pq}, \quad I_7 = a_{pr}^\alpha a_{\alpha q}^\beta a_{\beta s}^\gamma a_{\gamma \delta}^\delta \varepsilon^{pq} \varepsilon^{rs}, \quad I_8 = a_{pr}^\alpha a_{\alpha q}^\beta a_{\delta s}^\gamma a_{\beta \gamma}^\delta \varepsilon^{pq} \varepsilon^{rs}, \\
I_9 &= a_{pr}^\alpha a_{\beta q}^\beta a_{\gamma s}^\gamma a_{\alpha \delta}^\delta \varepsilon^{pq} \varepsilon^{rs}, \quad K_3 = a_\alpha^\alpha a_{\alpha \gamma}^\beta x^\gamma, \quad K_4 = a_\gamma^\alpha a_{\alpha \beta}^\beta x^\gamma, \\
K_5 &= a_{\alpha \beta}^p x^\alpha x^\beta x^q \varepsilon^{pq}, \quad K_6 = a_{\alpha \beta}^\alpha a_{\gamma \delta}^\beta x^\gamma x^\delta, \quad K_7 = a_{\beta \gamma}^\alpha a_{\alpha \delta}^\beta x^\gamma x^\delta, \\
K_{11} &= a_\alpha^p a_{\beta \gamma}^\alpha x^\beta x^\gamma x^q \varepsilon_{pq}, \quad K_{12} = a_{\beta \alpha}^\alpha a_{\alpha \gamma}^\beta a_{\delta \mu}^\gamma x^\delta x^\mu, \quad K_{13} = a_\gamma^\alpha a_{\alpha \beta}^\beta a_{\delta \mu}^\gamma x^\delta x^\mu, \\
K_{17} &= a_{\beta \nu}^\alpha a_{\alpha \gamma}^\beta a_{\delta \mu}^\gamma x^\delta x^\mu x^\nu, \quad K_{21} = a^p x^q \varepsilon_{pq}, \quad K_{23} = a^p a_{\alpha \beta}^q x^\alpha x^\beta \varepsilon_{pq}.
\end{aligned} \tag{6}$$

According to [3], write a transvectant of index  $k$  for binary forms  $f$  and  $\varphi$  as follows

$$(f, \varphi)^{(k)} = \sum_{h=0}^k (-1)^h \binom{k}{h} \frac{\partial^k f}{\partial x^{k-h} \partial y^h} \frac{\partial^k \varphi}{\partial x^h \partial y^{k-h}}. \tag{7}$$

According to [4], the transvectant (7) on two comitants of the system (1) is a comitant (invariant) of this system too.

For the system (1) from [4] will use the following transvectants

$$T_5 = (C, K)^{(2)}, \quad T_{16} = (C, D)^{(1)}, \tag{8}$$

where  $C = K_5$ ,  $D = I_1 K_1 K_2 + K_2 K_3 - K_2 K_4 + \frac{1}{2} I_1^2 K_5 - \frac{1}{2} I_2 K_5 - I_1 K_{11} - 2K_1^2 K_{21} + 4K_6 K_{21} - 2K_7 K_{21}$ ,  $K = \frac{1}{2}(K_1^2 - K_7)$ .

Denote by  $\tilde{a}(\tau)$  the point from the space  $E^{12}(\tilde{a})$ , that corresponds to the system, obtained from the system (1) with coefficients  $\tilde{a}$  by the transformation of translation  $\tau : x = \bar{x} + x_0$ ,  $y = \bar{y} + y_0$ . It is evident  $\tilde{a}(\tau) = \tilde{a}(x_0, y_0)$ . According to [6], if  $I(\tilde{a})$  is the center-affine invariant of the system (1), then the polynomial

$$K(\tilde{a}, x, y) = I(\tilde{a}(x_0, y_0))|_{\{x_0=x, y_0=y\}}$$

is a affine comitant of this system. Then considering (6), we construct the following affine comitants:

$$A f_i(\tilde{a}, x, y) = I_i(\tilde{a}(x_0, y_0))|_{\{x_0=x, y_0=y\}} \quad (i = 3, 4, 5). \tag{9}$$

**Lemma 1.** For  $\beta \neq 0$ , the rang of matrix  $M_1$  is equal to six, where

$$\beta = 27I_8 - I_9 - 18I_7 \tag{10}$$

and  $I_8, I_9, I_7$  are from (6).

*Proof.* We suppose the contrary  $\beta \neq 0$ , and all minors of the sixth order of the matrix  $M_1$  are zero. We observe that  $\beta$  is the discriminant of the cubic form  $K_5$ . It is known [2] that for  $\beta \neq 0$  there exists a linear transformation of the system (1). Such that the comitant  $K_5$  from (6) evaluated for the transformed system takes the form:

$$K_5 = x(x^2 + \delta y^2), \quad (\delta = \pm 1, l = -1, k = 0, g = 2m, n = 2h - \delta). \quad (11)$$

In case of (10) we obtain  $\Delta_{3,4,7,8,9,10} = -16\delta h^4 = 0$ ,  $\delta \neq 0$ , this implies  $h = 0$ . Taking into consideration  $h = 0$ , we obtain  $\Delta_{3,6,7,9,11,12} = -16\delta^4 m^2 = 0$ , this implies  $m = 0$ . Taking into consideration  $m = 0$ , we obtain  $\Delta_{5,6,9,10,11,12} = 8\delta^4 \neq 0$ . We obtain a contradiction. Lemma 1 is proved.  $\square$

**Lemma 2.** For  $K_5 \neq 0$ ,  $\beta = 0$ , the rang of matrix  $M_1$  is equal to six if and only if

$$Af_5^2 + T_5^2 + T_{16}^2 + Kom^2 \neq 0, \quad (12)$$

where

$$\begin{aligned} Kom \equiv & I_1 K_1^2 (2K_1^2 K_2 - 2K_2 K_6 - K_1 K_{11}) - 2K_1^3 (K_2 K_4 + 2K_7 K_{21}) + \\ & + 4K_1 K_6^2 K_{21} + K_1^2 [2K_4 K_{11} + K_2 K_{13} + 2K_{23} (K_6 + K_7)] - 4K_6^2 K_{23}, \end{aligned} \quad (13)$$

and  $I_1, K_1, K_2, K_4, K_5, K_6, K_7, K_{11}, K_{12}, K_{13}, K_{16}, K_{17}, K_{21}, K_{23}$  are from (6),  $T_5, T_{16}$  are from (8),  $\beta$  is from (9),  $Af_5$  is affine comitant of the system (1).

*Proof.* It is known from [2] that for  $K_5 \neq 0$  and  $\beta = 0$  there exists such affine transformation exists that the comitant  $K_5$  will take the form:

$$K_5 = x^2(x + \delta y), \quad (\delta = 0, 1; l = -1, k = 0, g = 2m + \delta, n = 2h). \quad (14)$$

Let (12) be not true. It is easy to verify that in case (14)  $T_5 \equiv 8h^2\delta y + 8h(3h - 2m\delta - \delta^2)x$ , from  $T_5 \equiv 0$  we have  $h = 0$ . Taking into consideration  $h = 0$  in the case (14), we obtain  $Af_5 \equiv -d(\delta^2 + 4m\delta + 5m^2)$ . From  $Af_5 \equiv 0$  it follows

$$d[\delta + (1 - \delta)m] = 0, \quad (\delta = 0, 1) \quad (15)$$

In the case  $\delta = 1$  from (15) we obtain  $d = 0$ ,  $T_{16} \equiv 6m(cf + ef - f^2 - 2am - 2bm)x^4$ , and  $Kom$  is the  $CT$  comitant [5],  $Kom \equiv (1 + 3m)^3(cf + ef - f^2 - 2am - 2bm)x^6$ . It is evident if  $T_{16} \equiv Kom \equiv 0$ , we obtain:

$$h = d = cf + ef - f^2 - 2am - 2bm = 0. \quad (16)$$

In the case when  $\delta = 0$  from (15) we obtain:  $m = 0$ ,  $Kom \equiv 0$ ,  $T_{16} \equiv 6dfx^4 - 6d^2x^3y$  or  $d = 0$ ,  $Kom \equiv 27m^3(cf - f^2 - 2am)x^6$ ,  $T_{16} \equiv 6m(cf - f^2 - 2am)x^4$ . It is evident if  $T_{16} \equiv Kom \equiv 0$  it follows:

$$h = d = m(cf - f^2 - 2am) = 0. \quad (17)$$

It is easy to verify that in cases (16), (17) all 6<sup>th</sup> order minors of the matrix  $M_1$  are equal to zero. The necessity of Lemma 2 is proved.

Prove the sufficiency. In the case when (14) holds for  $\delta = 1$  we obtain:  $\Delta_{3,4,7,8,11,12} = -8h^4$ , for  $h = 0$   $\Delta_{1,3,4,6,7,11} = 2d^3(1 + 3m)^2$ ,  $\Delta_{4,5,6,10,11,12} = -8dm^4$ ;

for  $h = d = 0$   $\Delta_{2,5,6,10,11,12} = 4m^3(cf + ef - f^2 - 2am - 2bm)$ ,  $\Delta_{2,3,5,7,10,11} = 2(1 + 2m)(1 + 3m)(cf + ef - f^2 - 2am - 2bm)$ .

In the case when (14) holds for  $\delta = 0$  we obtain:  $\Delta_{3,4,7,8,10,11} = -24h^4$ , for  $h = 0$   $\Delta_{1,3,4,6,7,11} = 18d^3m^2$ ; for  $h = m = 0$ ,  $\Delta_{1,3,4,5,7,10} = 2d^3$ . If  $h = d = 0$ , we obtain  $\Delta_{2,3,5,7,10,11} = 12m^2(cf - f^2 - 2am)$ . Lemma 2 is proved.  $\square$

**Lemma 3.** *For  $K_5 \equiv 0$ , the rang of matrix  $M_1$  is equal to six if and only if  $Af_4(Af_4 - Af_3) \neq 0$ , where  $Af_3, Af_4$  are affine comitants of the system (1).*

*Proof.* For  $K_5 \equiv 0$ , according to (2), (6) ( $l = k = 0$ ,  $g = 2m$ ,  $n = 2h$ ) we obtain that  $Af_4(Af_4 - Af_3) \equiv 27(eh^2 + chm + fhm - dm^2)^2$ , and all 6<sup>th</sup> order minors of the matrix  $M_1$  consist of the factor expression  $eh^2 + chm - fhm - dm^2$ . Taking into consideration the above mentioned proof of the Lemma 3 follows.  $\square$

From Lemmas 1,2,3 follows:

**Theorem.** *The dimension of  $Aff(2, \mathbb{R})$ -orbit of the system (1) is equal to six if and only if*

$$\begin{aligned} &\beta \neq 0, \text{ or} \\ &\beta = 0, K_5(Af_5^2 + T_5^2 + T_{16}^2 + Kom^2) \neq 0, \text{ or} \\ &\beta = 0, K_5 \equiv 0, Af_4(Af_4 - Af_3) \neq 0, \end{aligned}$$

where  $K_5$  from (6),  $T_5, T_{16}$  from (8),  $\beta$  from (9),  $Kom$  from (13),  $Af_3, Af_4, Af_5$  from (9) are affine comitants of the system (1).

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