

Multi-dimensional Darboux type differential systems with quadratic nonlinearities

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Abstract. In the article the n -dimensional autonomous Darboux type differential systems with nonlinearities of the 2^{nd} degree are considered. With the aid of theorem on integrating factor the particular invariant $GL(n, \mathbb{R})$ -integrals are constructed as well as the first integrals of Darboux type for considered systems. These integrals represent the algebraic curves of the 1^{st} degree. The recurrence formula of particular invariant $GL(n, \mathbb{R})$ -integrals of the Darboux type differential system is found.

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Consider the system of differential equations

$$\frac{dx^j}{dt} = a_{\alpha}^j x^{\alpha} + a_{\alpha\beta}^j x^{\alpha} x^{\beta} \equiv P^j(x, a) \quad (j, \alpha, \beta = \overline{1, n}; n \geq 2), \quad (1)$$

where coefficient tensor $a_{\alpha\beta}^j$ is symmetrical in lower indices, in which the complete convolution holds. The system (1) is considered with the action of the group $GL(n, \mathbb{R})$ of center-affine transformations [1], and $x = (x^1, x^2, \dots, x^n)$ is a phase variable vector of the system.

Suppose that system (1) admits $(n - 1)$ -dimensional commutative Lie algebra with operators

$$X_{\alpha} = \xi_{\alpha}^j(x) \frac{\partial}{\partial x^j} \quad (j = \overline{1, n}; \alpha = \overline{1, n-1}) \quad (2)$$

and

$$\Lambda = P^j(x, a) \frac{\partial}{\partial x^j} \quad (j = \overline{1, n}). \quad (3)$$

Consider the determinant constructed on coordinates of operators (2)-(3) as follows

$$\Delta = \begin{vmatrix} \xi_1^1 & \xi_1^2 & \xi_1^3 & \dots & \xi_1^n \\ \xi_2^1 & \xi_2^2 & \xi_2^3 & \dots & \xi_2^n \\ \dots & \dots & \dots & \dots & \dots \\ \xi_{n-1}^1 & \xi_{n-1}^2 & \xi_{n-1}^3 & \dots & \xi_{n-1}^n \\ P^1 & P^2 & P^3 & \dots & P^n \end{vmatrix}. \quad (4)$$

From [2] it follows that holds

Theorem 1. *If n -dimensional differential system (1) admits $(n - 1)$ -dimensional commutative Lie algebra of operators (2), then the function $\mu = \frac{1}{\Delta}$, where $\Delta \neq 0$ from (4), is the integrating factor for Pfaff equations*

$$\sum_{i=1}^n (-1)^{i+j} \begin{vmatrix} \xi_1^1 & \dots & \xi_1^{i-1} & \xi_1^{i+1} & \dots & \xi_1^n \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \xi_{j-1}^1 & \dots & \xi_{j-1}^{i-1} & \xi_{j-1}^{i+1} & \dots & \xi_{j-1}^n \\ \xi_{j+1}^1 & \dots & \xi_{j+1}^{i-1} & \xi_{j+1}^{i+1} & \dots & \xi_{j+1}^n \\ \dots & \dots & \dots & \dots & \dots & \dots \\ P^1 & \dots & P^{i-1} & P^{i+1} & \dots & P^n \end{vmatrix} dx^i = 0 \quad (i = \overline{1, n}; j = \overline{1, n-1}), \quad (5)$$

defining a general integral of the system (1).

Following [3], consider system (1) in a "Darboux" like case, i.e. system (1) written in the form

$$\frac{dx^j}{dt} = a_{\alpha}^j x^{\alpha} + 2x^j R(x) \equiv P^j(x, a) \quad (j, \alpha = \overline{1, n}; n \geq 2), \quad (6)$$

where $R(x) \neq 0$ is a homogeneous linear polynomial with constant coefficients in coordinates of the vector x .

According to [4] will treat invariant $GL(n, \mathbb{R})$ -integrating factors and invariant $GL(n, \mathbb{R})$ -integrals of the system (6) with $n = 2, 3, 4, 5, \dots$

1. Case $n = 2$. Will denote the invariants and comitants of the system (1) as follows

$$\begin{aligned} I_{1,2} &= a_{\alpha_1}^{\alpha_1}, & I_{2,2} &= a_{\alpha_2}^{\alpha_1} a_{\alpha_1}^{\alpha_2}, & K_{1,2} &= a_{\alpha}^{\alpha_1} x^{\alpha} x^{\alpha_2} \varepsilon_{\alpha_1 \alpha_2}, \\ P_{1,2} &= a_{\alpha_1 \beta}^{\alpha_1} x^{\beta}, & P_{2,2} &= a_{\alpha_2}^{\alpha_1} a_{\alpha_1 \beta}^{\alpha_2} x^{\beta}, & \tilde{K}_{1,2} &= a_{\beta \gamma}^{\alpha_1} x^{\beta} x^{\gamma} x^{\alpha_2} \varepsilon_{\alpha_1 \alpha_2}, \end{aligned} \quad (7)$$

where the first of lower indices for I, K, P and \tilde{K} from (7) shows the degree of invariant or comitant with respect to coefficients of the system (1), and the second lower index shows the dimension of the system ($n = 2$). In [4] it is shown that invariant condition which differs the system (6) from (1) is the following: $\tilde{K}_{1,2} \equiv 0$. In the same paper with the aid of Theorem 1 and expressions (7) is proved

Theorem 2. *System (1) with $\tilde{K}_{1,2} \equiv 0$ and $n = 2$ has the invariant $GL(2, \mathbb{R})$ -integrating factor μ of the form $\mu^{-1} = K_{1,2} \Phi_{2,2}$, where $K_{1,2} = 0$ and*

$$\Phi_{2,2} \equiv 8I_{1,2}P_{1,2} - 12P_{2,2} + 3(I_{1,2}^2 - I_{2,2}) = 0$$

are invariant particular $GL(2, \mathbb{R})$ -integrals of this system.

2. Case $n = 3$. Following [3] will denote the invariants, comitants and covariants of the system (1) as follows

$$\begin{aligned}
I_{1,3} &= a_{\alpha_1}^{\alpha_1}, \quad I_{2,3} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1}^{\alpha_2}, \quad I_{3,3} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3}, \\
K_{3,3} &= a_{\alpha_1}^{\beta_1} a_{\alpha_2}^{\beta_2} a_{\alpha_3}^{\alpha_2} x^{\alpha_1} x^{\alpha_3} x^{\beta_3} \varepsilon_{\beta_1 \beta_2 \beta_3}, \\
P_{1,3} &= a_{\alpha_1 \beta}^{\alpha_1} x^\beta, \quad P_{2,3} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1 \beta}^{\alpha_2} x^\beta, \quad P_{3,3} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2 \beta}^{\alpha_3} x^\beta, \\
\tilde{K}_{1,3} &= a_{\beta \gamma}^{\alpha_1} x^\beta x^\gamma x^{\alpha_2} x_1^{\alpha_3} \varepsilon_{\alpha_1 \alpha_2 \alpha_3},
\end{aligned} \tag{8}$$

where the meaning of the lower indices for I, K, P and \tilde{K} is the same, and the vector $x_1 = (x_1^1, x_1^2, x_1^3)$ is cogradient [5] to the phase variable vector $x = (x^1, x^2, x^3)$. The vectors x and x_1 are independent. In [3] it is shown that invariant condition which differs the system (6) from (1) is the following: $\tilde{K}_{1,3} \equiv 0$. In the same paper with the aid of Theorem 1 and expressions (8) is proved

Theorem 3. *System (1) with $\tilde{K}_{1,3} \equiv 0$ and $n = 3$ has the invariant $GL(3, \mathbb{R})$ -integrating factor μ of the form $\mu^{-1} = K_{3,3} \Phi_{3,3}$, where $K_{3,3} = 0$ and*

$$\Phi_{3,3} \equiv 1/3(I_{1,3}^2 - 3I_{1,3}I_{2,3} + 2I_{3,3}) - 3/2(I_{2,3} - I_{1,3}^2)P_{1,3} - 4I_{1,3}P_{2,3} + 4P_{3,3} = 0$$

are invariant particular $GL(3, \mathbb{R})$ -integrals of this system.

3. Case $n = 4$. Consider the next invariants, comitants and covariants of the system (1)

$$\begin{aligned}
I_{1,4} &= a_{\alpha_1}^{\alpha_1}, \quad I_{2,4} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1}^{\alpha_2}, \quad I_{3,4} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3}, \quad I_{4,4} = a_{\alpha_4}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3}^{\alpha_4}, \\
K_{6,4} &= a_{\alpha_1}^{\beta_1} a_{\alpha_2}^{\beta_2} a_{\alpha_3}^{\alpha_2} a_{\alpha_4}^{\beta_3} a_{\alpha_5}^{\alpha_4} a_{\alpha_6}^{\alpha_5} x^{\alpha_1} x^{\alpha_3} x^{\alpha_6} x^{\beta_4} \varepsilon_{\beta_1 \beta_2 \beta_3 \beta_4}, \quad P_{1,4} = a_{\alpha_1 \beta}^{\alpha_1} x^\beta, \\
P_{2,4} &= a_{\alpha_2}^{\alpha_1} a_{\alpha_1 \beta}^{\alpha_2} x^\beta, \quad P_{3,4} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2 \beta}^{\alpha_3} x^\beta, \quad P_{4,4} = a_{\alpha_4}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3 \beta}^{\alpha_4} x^\beta, \\
\tilde{K}_{1,4} &= a_{\beta \gamma}^{\alpha_1} x^\beta x^\gamma x^{\alpha_2} x_1^{\alpha_3} x_2^{\alpha_4} \varepsilon_{\alpha_1 \alpha_2 \alpha_3 \alpha_4},
\end{aligned} \tag{9}$$

where the meaning of the lower indices for I, K, P and \tilde{K} is the same, and the vectors $x_1 = (x_1^1, x_1^2, x_1^3, x_1^4)$ and $x_2 = (x_2^1, x_2^2, x_2^3, x_2^4)$ are cogradient to the phase variable vector x . One can verify easily that invariant condition which differs the system (6) from (1) is the following: $\tilde{K}_{1,4} \equiv 0$. With the aid of Theorem 1 and expressions (9) it is proved the following

Theorem 4. *System (1) with $\tilde{K}_{1,4} \equiv 0$ and $n = 4$ has the invariant $GL(4, \mathbb{R})$ -integrating factor μ of the form $\mu^{-1} = K_{6,4} \Phi_{4,4}$, where $K_{6,4} = 0$ and*

$$\Phi_{4,4} \equiv L_{4,4} - 2(4/5L_{3,4}P_{1,4} + L_{2,4}P_{2,4} + L_{1,4}P_{3,4} + P_{4,4}) = 0 \tag{10}$$

are invariant particular $GL(4, \mathbb{R})$ -integrals of this system. In (10) we have

$$L_{1,4} = -I_{1,4}, \quad L_{2,4} = 1/2(I_{1,4}^2 - I_{2,4}), \quad L_{3,4} = 1/6(3I_{1,4}I_{2,4} - 2I_{3,4} - I_{1,4}^3),$$

$$L_{4,4} = 1/24(8I_{1,4}I_{3,4} - 6I_{4,4} - 6I_{1,4}^2I_{2,4} + 3I_{2,4}^2 + I_{1,4}^4),$$

where $I_{k,4}$ ($k = \overline{1,4}$) are from (9).

4. Case $n = 5$. Consider the next invariants, comitants and covariants of the system (1)

$$\begin{aligned}
I_{1,5} &= a_{\alpha_1}^{\alpha_1}, \quad I_{2,5} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1}^{\alpha_2}, \quad I_{3,5} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3}, \\
I_{4,5} &= a_{\alpha_4}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3}^{\alpha_4}, \quad I_{5,5} = a_{\alpha_5}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3}^{\alpha_4} a_{\alpha_4}^{\alpha_5}, \\
K_{10,5} &= a_{\alpha_1}^{\beta_1} a_{\alpha_2}^{\beta_2} a_{\alpha_3}^{\alpha_2} a_{\alpha_4}^{\beta_3} a_{\alpha_5}^{\alpha_4} a_{\alpha_6}^{\alpha_5} a_{\alpha_7}^{\beta_4} a_{\alpha_8}^{\alpha_7} a_{\alpha_9}^{\alpha_8} a_{\alpha_{10}}^{\alpha_9} x^{\alpha_1} x^{\alpha_3} x^{\alpha_6} x^{\alpha_{10}} x^{\beta_5} \varepsilon_{\beta_1 \beta_2 \beta_3 \beta_4 \beta_5}, \\
P_{1,5} &= a_{\alpha_1 \beta}^{\alpha_1} x^\beta, \quad P_{2,5} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1 \beta}^{\alpha_2} x^\beta, \quad P_{3,5} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2 \beta}^{\alpha_3} x^\beta, \\
P_{4,5} &= a_{\alpha_4}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3 \beta}^{\alpha_4} x^\beta, \quad P_{5,5} = a_{\alpha_5}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} a_{\alpha_3}^{\alpha_4} a_{\alpha_4 \beta}^{\alpha_5} x^\beta, \\
\tilde{K}_{1,5} &= a_{\beta \gamma}^{\alpha_1} x^\beta x^\gamma x^{\alpha_2} x_1^{\alpha_3} x_2^{\alpha_4} x_3^{\alpha_5} \varepsilon_{\alpha_1 \alpha_2 \alpha_3 \alpha_4 \alpha_5},
\end{aligned} \tag{11}$$

where the meaning of lower indices for I, K, P and \tilde{K} is the same, and the vectors $x_i = (x_i^1, x_i^2, x_i^3, x_i^4, x_i^5)$, ($i = \overline{1, 5}$) are cogradient to the phase variable vector x . As it is easy to see the invariant condition which differs the system (6) from (1) is the following: $\tilde{K}_{1,5} \equiv 0$. With the aid of Theorem 1 and expressions (11) is proved the following

Theorem 5. *System (1) with $\tilde{K}_{1,5} \equiv 0$ and $n = 5$ has the invariant $GL(5, \mathbb{R})$ -integrating factor μ of the form $\mu^{-1} = K_{10,5} \Phi_{5,5}$, where $K_{10,5} = 0$ and*

$$\Phi_{5,5} \equiv L_{5,5} - 2(5/6 L_{4,5} P_{1,5} + L_{3,5} P_{2,5} + L_{2,5} P_{3,5} + L_{1,5} P_{4,5} + P_{5,5}) = 0 \tag{12}$$

are invariant particular $GL(5, \mathbb{R})$ -integrals of this system. In (12) we have

$$\begin{aligned}
L_{1,5} &= -I_{1,5}, \quad L_{2,5} = 1/2(I_{1,5}^2 - I_{2,5}), \quad L_{3,5} = 1/6(3I_{1,5}I_{2,5} - 2I_{3,5} - I_{1,5}^3), \\
L_{4,5} &= 1/24(8I_{1,5}I_{3,5} - 6I_{4,5} - 6I_{1,5}^2I_{2,5} + 3I_{2,5}^2 + I_{1,5}^4), \\
L_{5,5} &= -1/120(I_{1,5}^5 - 10I_{1,5}^3I_{2,5} + 20I_{1,5}^2I_{3,5} + 15I_{1,5}I_{2,5}^2 - 30I_{1,5}I_{4,5} - 20I_{2,5}I_{3,5} + 24I_{5,5}),
\end{aligned}$$

where $I_{k,5}$ ($k = \overline{1, 5}$) are from (11).

5. The general case $n \geq 2$.

Write the center-affine invariants, comitants and covariants in general case of system (1) as follows

$$\begin{aligned}
I_{1,n} &= a_{\alpha_1}^{\alpha_1}, \quad I_{2,n} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1}^{\alpha_2}, \quad I_{3,n} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3}, \dots, \quad I_{n,n} = a_{\alpha_n}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} \dots a_{\alpha_{n-1}}^{\alpha_n}, \\
K_{m,n} &= a_{\alpha_1}^{\beta_1} a_{\alpha_2}^{\beta_2} a_{\alpha_3}^{\alpha_2} a_{\alpha_4}^{\beta_3} a_{\alpha_5}^{\alpha_4} a_{\alpha_6}^{\alpha_5} a_{\alpha_7}^{\beta_4} a_{\alpha_8}^{\alpha_7} a_{\alpha_9}^{\alpha_8} a_{\alpha_{10}}^{\alpha_9} \dots a_{\alpha_m}^{\alpha_{m-1}} x^{\alpha_1} x^{\alpha_3} x^{\alpha_6} x^{\alpha_{10}} \dots x^{\alpha_m} x^{\beta_n} \varepsilon_{\beta_1 \dots \beta_n}, \\
P_{1,n} &= a_{\alpha_1 \beta}^{\alpha_1} x^\beta, \quad P_{2,n} = a_{\alpha_2}^{\alpha_1} a_{\alpha_1 \beta}^{\alpha_2} x^\beta, \quad P_{3,n} = a_{\alpha_3}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2 \beta}^{\alpha_3} x^\beta, \dots, \\
P_{n,n} &= a_{\alpha_n}^{\alpha_1} a_{\alpha_1}^{\alpha_2} a_{\alpha_2}^{\alpha_3} \dots a_{\alpha_{n-1} \beta}^{\alpha_n} x^\beta, \\
\tilde{K}_{1,n} &= a_{\alpha \beta}^{\beta_1} x^\alpha x^\beta x^{\beta_2} x_1^{\beta_3} x_2^{\beta_4} \dots x_{n-2}^{\beta_n} \varepsilon_{\beta_1 \beta_2 \dots \beta_n}, \\
(\alpha, \alpha_1, \alpha_2, \dots, \alpha_m, \dots, \alpha_n, \beta, \beta_1, \beta_2, \dots, \beta_n = \overline{1, n}; \quad m = \frac{n(n-1)}{2}; \quad n \geq 2)
\end{aligned} \tag{13}$$

where $\varepsilon_{\beta_1\beta_2\beta_3\dots\beta_n}$ is a unit n -vector, and the vectors $x_i = (x_i^1, x_i^2, \dots, x_i^n)$, ($i = \overline{1, n-2}$) are independent cogradient vectors [5] to x .

Remark 1. System (1) with $\tilde{K}_{1,n} \equiv 0$ has the form (6), where $R(x) = \frac{1}{n+1}P_{1,n}$.

Will call the systems written in the form (6) a Darboux type differential system (analogically to the case when $n = 2$ in [4]).

As it is easy to see the center-affine invariant condition differ the system (6) from (1). Indeed, it is true that for system (6) with $\tilde{K}_{1,n} \equiv 0$, we have $P_{1,n} = (n+1)R(x)$.

One can verify that the next theorem generalizes cases 1-4

Theorem 6. *System (1) with $\tilde{K}_{1,n} \equiv 0$ and $n = 2, 3, 4, 5$ has the invariant $GL(n, \mathbb{R})$ -integrating factor μ of the form*

$$\mu^{-1} = K_{m,n}\Phi_{n,n},$$

where $K_{m,n} = 0$ and

$$\Phi_{n,n} \equiv L_{n,n} - 2\left(\frac{n}{n+1}L_{n-1,n}P_{1,n} + L_{n-2,n}P_{2,n} + L_{n-3,n}P_{3,n} + \dots + L_{1,n}P_{n-1,n} + P_{n,n}\right) = 0 \quad (14)$$

are invariant particular $GL(n, \mathbb{R})$ -integrals of this system, and $L_{i,n}$ ($i = \overline{1, n}$) are the coefficients of characteristic equation of the system (1) as follows

$$\lambda^n + L_{1,n}\lambda^{n-1} + L_{2,n}\lambda^{n-2} + \dots + L_{n-1,n}\lambda + L_{n,n} = 0 \quad (15)$$

and they can be expressed through the invariants from (13) by the recurrence formula

$$L_{i,n} = -\frac{1}{i}(I_{i,n} + I_{i-1,n}L_{1,n} + I_{i-2,n}L_{2,n} + \dots + I_{1,n}L_{i-1,n}) \quad (i = \overline{1, n}). \quad (16)$$

With the aid of the cases 1-4 it is easy to verify that holds the next

Theorem 7. *System (1) with $\tilde{K}_{1,n} \equiv 0$ and $n = 2, 3, 4, 5$ has the first invariant $GL(n, \mathbb{R})$ -integral of Darboux type [6] as follows*

$$K_{m,n}^{-1}\Phi_{n,n}^n = C \quad (17)$$

if and only if $I_{1,n} = 0$, where $K_{m,n}$, $\tilde{K}_{1,n}$, $I_{1,n}$ are from (13), and $\Phi_{n,n}$ is from (14).

The proof of Theorem 7 for system (6) follows from the equation

$$\Lambda(K_{m,n}^{-1}\Phi_{n,n}^n) = -I_1K_{m,n}^{-1}\Phi_{n,n}^n,$$

where Λ is from (3).

Remark 2. There exists the assumption that Theorems 6 and 7 hold for $n \geq 6$.

One can verify that holds

Remark 3. Expression $K_{m,n} = 0$ from (13) is the invariant particular $GL(n, \mathbb{R})$ -integral for linear system $\frac{dx^j}{dt} = a_\alpha^j x^\alpha$ ($\alpha = \overline{1, n}$).

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